Riveting/clinching unit TOX

Technical data

Pressing and nominal force
Total stroke
Max. piston speed
Machine, gripper No.
TE-X

Measuring configuration

• Force sensor measuring range 5 % - 100 % of the nominal force

Measuring precision (force)
< ±1 % of the nominal force

Force sensor sensitivity 0-10 VDC / ±20 mA

Reproducibility < ±0.01 mm

Fields of use / applications

• Joining process characterisation and process parameter variation during clinching and riveting

• Function-controlled programming of joining work flows by means of complex programs

• Electromechanical servo drive for exact monitoring and control of pressing and joining processes

• Available dies: Clinching (6 mm, 8 mm and 10 mm); solid rivets (4 mm and 5 mm); half-hollow rivets (3.3 and 5.3 mm)



